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### Why is verification of NNs important?

- Safety critical applications
	- Safety is a concern
	- Lives /money/ personal information at risk
- Applications such as:
	- Medical diagnosis
	- Self driving vehicles
	- Financial systems







#### Why is verification of NNs important?



"panda" 57.7% confidence

Source: Goodfellow, I. J., Shlens, J., & Szegedy, C. (2014). Explaining and harnessing adversarial example



"nematode" 8.2% confidence



- 
- By adding  $\epsilon$  (an imperceptibly small vector) to the input vector, classification changes with a high confidence!



# • Szegedy et al. (2013), Goodfellow et al. (2014) observe a curious phenomenon



### Why is verification of NNs important?

- Safety critical applications
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#### Feed-Forward Neural Networks

- Neural network  $f: \mathbb{R}^n \to \mathbb{R}^m$  modeled as a DAG,  $G = (V, E)$ 
	- V: finite set of nodes
	- $E ⊆ V × V$ : finite set of edges
- Nodes V partitioned into *l* layers  $V^i$  with  $1 \leq i \leq l$ 
	- $V^1$ : input layer
	- $V^2, …, V^{l-1}$ : hidden layers







#### Feed-Forward Neural Networks









- Most used activation function
- $ReLU(x) = max(0, x)$



#### Activation Functions



ReLU (Rectified Linear Unit)

Activation functions help introduce non-linearity which helps model complex functions, ones that cannot be modeled with plain linear regression



Source: towardsdatascience.com

#### Activation Functions

#### **Sigmoid**



•The output of sigmoid lies between 0 and 1

•Therefore used for models where a probability needs to be predicted as the output

Sigmoid  $(z) = 1/(1 + e^{\Lambda(-z)})$ 



#### Activation Functions

#### **Softmax**



- Softmax turns a vector of K real values into a vector of K real values that sum to 1
- It is used to obtain the confidence scores for NN output labels

$$
Softmax(z) = \frac{e^{z_i}}{\sum_{j=1}^{N} e^{z_j}}
$$







- In neural networks used as classifiers, input  $\vec{x}$  mapped to one of m classes
- Final layer typically employs a softmax function to represent output as normalized probabilities
- We use the term confidence,  $conf(f(\vec{x}))$ to refer to the highest probability



### $conf(f(\vec{x})) = max(out(v_{l,1}), ..., out(v_{l,n}))$

#### Confidence score

# $\|\vec{x} - \vec{x_0}\| \le \epsilon \to \text{class}(f(\vec{x})) = \text{class}(f(\vec{x_0}))$

This is called local robustness because we are checking for perturbations in an  $\epsilon$ -radius circle around a fixed  $\overrightarrow{x_o}$ 

#### State-of-art

Local robustness - NN's ability to withstand adversarial inputs in the vicinity of a specific point in the input space

"Small" changes in input -> "Small" changes in output





### State-of-art

# •SMT-based NN verification tools, such as Marabou [M1], take a fully-connected feed-forward

- neural network along with the local robustness property that needs to be verified
- •Network encoded as a set of linear constraints representing weighted sum of neurons' outputs and a set of non-linear constraints defining activation functions
- •The property is a set of constraints on the network's inputs and outputs
- The neurons are treated as variables the verification problem thus involves identifying a variable assignment that satisfies all constraints at the same time
- •Pass the constraints corresponding to the NN and the property (in negated form) to an SMT solver to find a satisfying assignment







- Local robustness is defined only for a specific input
- Consequently, it does not provide any guarantees for any other input
- It follows that the robustness of the entire neural network cannot be assessed with local robustness only



Narrow, limited approach

Need a broader perspective when certifying NNs - one that covers the entire input space

#### Local robustness - Limitations



- Global robustness is not limited to analyzing robustness around a fixed point
- points
- global robustness

• The local robustness definition that we saw can be generalized over all inputs to get

$$
\forall \vec{x}, \vec{x}' \ ||\vec{x} - \vec{x}'|| \le \epsilon \rightarrow \text{class}(f(\vec{x})) = \text{class}(f(\vec{x}'))
$$



• It is a measure of a NN's robustness over the entire input space, rather than specific

Global robustness - General Definition



Global robustness - **Limitation** 

#### $\forall \vec{x}, x' \|\vec{x} - x'\| \leq \epsilon \rightarrow \text{class}(f(\vec{x})) = \text{class}(f(x'))$  $\overline{a}$

- This definition of global robustness, however, can only be satisfied by trivial models that map all inputs to a single class
- NNs



• This needs to be relaxed in order to make it practically useful for verification of





#### Confidence-based global robustness

- At decision boundaries, the confidence for one label gradually decreases whereas the confidence in another one gradually increases
- At transition point, confidences in both labels lower and close to each other
- Hence, we do not consider pairs of inputs whose labels differ, but with a low level of confidence, to be counterexamples to robustness
- The idea is to compare all input pairs which are sufficiently close and for which at least one of them yields a high-confidence classification







**Solution** 

### Global Fairness

- CertiFair [C1] and Fairify [F1] address a similar problem, which arises in the context of fairness, by partitioning the input space based on categorical features
- In general, if the input to a decision-making neural network comprises of certain sensitive attributes, say age or gender, the network is said to be fair if the sensitive attributes do not influence its decision
- For example, a hiring algorithm that discriminates against certain groups of job applicants based on their race or gender could perpetuate existing biases and inequalities in the workplace



$$
\forall \vec{x} = (x_s, \vec{x_n}), \vec{x'} = (x'_s, \vec{x'_n}). \quad ||\vec{x_n} - \vec{x'_n}|| \le \epsilon \quad \land (x_s \neq x'_s) \rightarrow class(f(\vec{x})) = class(f(\vec{x'}))
$$

where  $x_s$  and  $x_{n}$  sensitive and non-sensitive attributes of  $\vec{x}$ , respectively YSEC

### Global robustness and fairness are hyperproperties

- Observe that global robustness and fairness are hyper properties
- Properties capture relationships between multiple execution traces are known as hyperproperties
- Traditional properties, in contrast, are evaluated over individual traces
- A hyperproperty on the other hand quantifies over more than one trace



$$
\forall \vec{x}. \text{conf}(f(\vec{x})) \ge \kappa \quad \text{Traditional property}
$$
\n
$$
\forall \vec{x}, \vec{x}'. \frac{f(\vec{x})_i - f(\vec{x}')_i}{||\vec{x} - \vec{x}'||} \le \kappa \quad \text{Hyperproperty}
$$



#### Global robustness and fairness are hyperproperties

• Observe that global robustness and fairness are hyperproperties



$$
(\overrightarrow{x_n}), \overrightarrow{x'} = (x'_s, \overrightarrow{x'_n}). \quad ||\overrightarrow{x_n} - \overrightarrow{x'_n}|| \le \epsilon \quad \land (x_s \neq x'_s) \rightarrow \overrightarrow{x_s}) = class(f(\overrightarrow{x'}))
$$

where  $x_{\!s}$  and  $x_{\!n\!}$  sensitive and non-sensitive attributes of  $\vec{x},$  respectively  $\ddot{a}$ 

• We used this striking similarity of the two properties to formalize the first definition of confidence-

based 2-safety property that unifies global robustness and fairness for DNNs





#### Confidence-based global 2-safety - **Definition**

• A model f is said to be globally 2-safe for confidence  $\kappa > 0$  and tolerance  $\epsilon$  iff:

⃗ ⃗

$$
\forall \vec{x}, \vec{x}'.cond(\vec{x}, \vec{x}', \vec{\epsilon}) \land conf(f(\vec{x})) > \kappa \implies class(f(\vec{x})) = class(f(\vec{x}'))
$$

For confidence-based global robustness:

$$
cond(\vec{x}, \vec{x}', \vec{\epsilon}) = \bigwedge_{i \in [1, n]} d(x_i, x'_i) \le \epsilon_i
$$



For confidence-based global fairness:

$$
cond(\vec{x}, \vec{x}', \vec{\epsilon}) = \bigwedge_{x_i \in \overline{x_s}} d(x_i, x'_i) > 0 \land \bigwedge_{x_i \in \overline{x_n}} d(x_i, x'_i) \le
$$



### Confidence-based global 2-safety - **Challenges**

- We have now crossed the first hurdle by defining the property that we want to check
- However, there are several challenges:
	- 1.How to verify a 2-safety property?
	- 2.The presence of confidence in the definition of the property means we have to deal with non-linear softmax





# 1. How to verify a 2-safety property?





### Self-composition



- 2-safety properties can be verified using selfcomposition
- The idea is to compose the program with itself and relate the two executions

where,  $(\vec{x},\,x')$ : concatenation of vectors  $\vec{x}$  and  $\lambda \vec{x}$  .  $f(\vec{x})$ : lambda term that binds  $\vec{x}$  in  $f(\vec{x})$  $f(\vec{x}) \times f(x') = \lambda(\vec{x}, x')$ .  $(f(\vec{x}), f(x'))$ ⃗  $(\vec{x}, x')$ : concatenation of vectors  $\vec{x}$  and  $x'$ ⃗

• A counterexample to a 2-safety property comprises of a pair of traces









- Compose a copy of the neural network with itself to get a product neural network
- The self-composed neural network consists of two copies of the original neural network, each with its own copy of the variables
- To encode the self-composition, we duplicate all variables and constraints by introducing primed counterparts in'<sub>i,j</sub> and out'<sub>i,j</sub> for  $in_{i,j}$  and out<sub>i,j</sub>
- Checking 2-safety then reduces to checking an ordinary safety property
- A product network allows the reduction of a 2-safety to a trace property, a problem, which can be solved using an existing standard verification technique





#### Encoding 2-safety as Product Neural Network

## 2. How to deal with non-linear softmax to model confidence







- $softmax(\vec{z}_i)$  =  $sigmoid(z_i LSE_i^n)$ 1 *j*≠*i* (*zj* ))
- $max_1^n(z_i) \leq LSE_1^n(z_i) \leq max_1^n(z_i) + log(n)$
- To model confidence, we needed a way to find an abstraction of the softmax, which is amenable to automated verification
- Our approximation of the softmax involves a 2-step approach
- In the first part of the approximation, we express softmax in terms of log-sum-exp (LSE) and sigmoid

#### Confidence - 2-step approach

#### **Step 1**

• We use these equations to express softmax in terms of sigmoid and max



⃗

• Also, from [P1] we know that:





#### Confidence - 2-step approach

#### **Step 2**

- We still do not know how to deal with sigmoid
- We approximate sigmoid as a piece-wise linear function using the Remez exchange algorithm [R1].
- Remez algorithm iterative algorithm that finds simpler approximations to functions
- Set error to 0.005 -> obtain 35 segments -> encode each segment as an equation and represent using variable q
- Select applicable segment





 $\epsilon$ 

**Theorem 3.** (Soundness) Let f and  $\hat{f}$  be the original neural network and overapproximated neural network, respectively. Let  $b_{n,\delta}$  be the error bound of the approximated softmax  $(b_{n,\delta} = \frac{n-2}{(\sqrt{n-1}+1)^2} + 2\delta$  (see Theorem<sup>1</sup>1)). Then we have the following soundness guarantee: Whenever the approximated neural network is 2safe for conf $(\hat{f}(\vec{x})) > (\kappa - b_{n,\delta})$ , the real neural network is 2-safe for conf $(f(\vec{x})) >$  $\kappa$ , given conf $(\hat{f}(\vec{x})) > \frac{1}{2}$ . Formally:

$$
\begin{aligned}\n\left(\forall \vec{x}, \vec{x'}. \text{ cond}(\vec{x}, \vec{x'}, \vec{\epsilon}) \land \text{conf}(\hat{f}(\vec{x})) > (\kappa - b_{n, \delta}) \\
\implies \text{class}(\hat{f}(\vec{x})) = \text{class}(\hat{f}(\vec{x'}))\n\end{aligned}\n\right) \implies
$$
\n
$$
\left(\forall \vec{x}, \vec{x'}. \text{ cond}(\vec{x}, \vec{x'}, \vec{\epsilon}) \land \text{conf}(\vec{f}(\vec{x})) > \kappa \right), \text{ with } \text{conf}(\hat{f}(\vec{x})) > \frac{1}{2}
$$

### **Soundness**

- For our confidence-based 2-safety property, our analysis provides a soundness guarantee
- This means that whenever the analysis reports that the property holds, then the property also holds true in the concrete execution







### Implementation

- Our method is applicable to any off-the-shelf static analysis tool
- As a proof of concept, we implement it on the state-of-the-art NN verification tool Marabou
- Simplex-based, linear programming verification tool
- Capable of addressing queries about network's properties (such as local robustness) by encoding them into constraint satisfaction problem
- Can only handle traditional safety properties







Verifying Global Two-Safety Properties in Neural Networks with Confidence

#### Experimental evaluation - Confidence-based global robustness



 $|S\&P$ 

Security<br>& Privacy

T

**WIEN** 



#### Experimental evaluation - Confidence-based global fairness



Global fairness on German credit/COMPAS datasets for various criteria





- We combined our method with binary search, to synthesize the minimum confidence for which the DNN is globally robust or fair
- We perform the binary search:
	- Start with confidence 0.5
	- If the model is unsat, done!
	- Else, check for confidence  $mid = (0.5 + 1)/2$ , and continue in this way till we find the minimum confidence accurate to the nearest 0.05
- For instance, binary search combined with our method, on German credit gave us 0.75 (in 45 seconds) to be the minimum confidence for which the DNN is globally robust



#### Exploring the space of property parameters



#### Current and Future Work

- Scalablility
	- Pruning
	- Knowledge distillation
- Tighter softmax approximation
- A hybrid approach that leverages the strengths of both testing and verification
- Property-based testing for our 2-safety confidence based property





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# Thank You! Questions?



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